

A Short Introduction to HUNTER: Human Unimodel for Nuclear Technology to Enhance Reliability

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- **We've divided HUNTER into five topics**
 - Introduction – Ron Boring
 - Task Module (= Procedures) – Tom Ulrich
 - Environment Module (= RELAP5-3D Interface) – Yun Heo
 - Individual Module (= Performance Shaping Factors) – Jooyoung Park
 - Graphical User Interface – Jeeyea Ahn
- **Represents work primarily from the period Summer 2021 – Spring 2022**





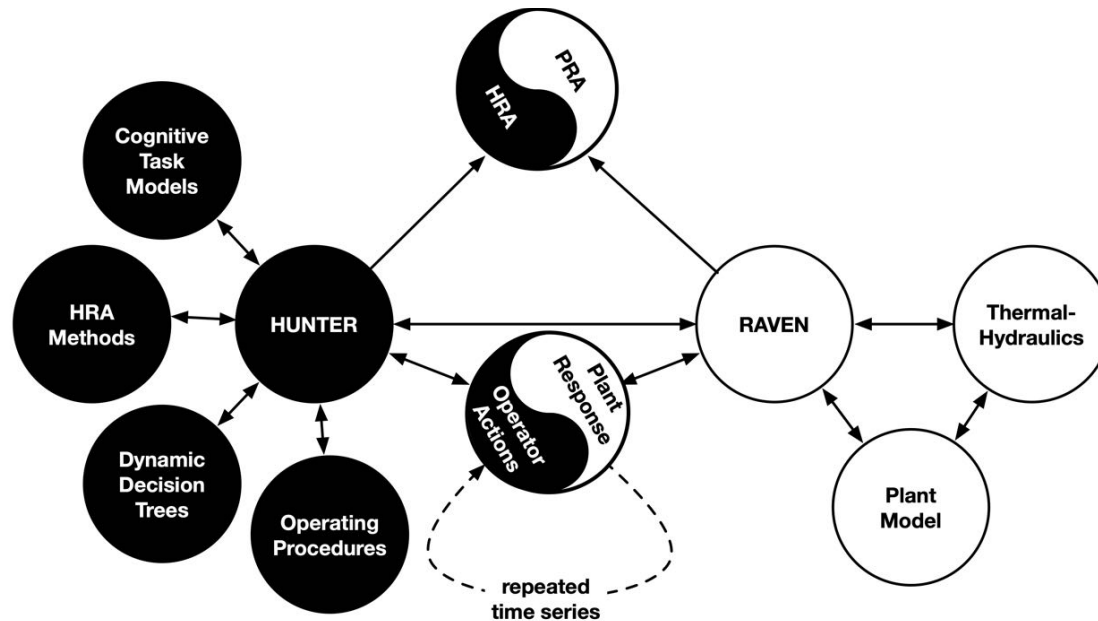
HUNTER Origins

What's in a Name?

- **HUNTER: Human Unimodel for Nuclear Technology to Enhance Reliability**
 - A *unimodel* is a cognitive framework that favors simplified decision models
 - The HUNTER name is a tongue-in-cheek reference to many of the INL animal-named modeling and simulation codes
 - HUNTER is the human element coupled to the hardware model, e.g., MOOSE-HUNTER or RAVEN-HUNTER
 - We disavow any reference to harming the animal-named codes we work with of course! 😊



- **HUNTER Introduced at PSAM in Korea**
 - Goal: Create a dynamic version of SPAR-H
 - Develop simple, easy-to-use dynamic HRA as proof of concept
 - Stepping stone to more complete dynamic HRA methods like ADS-IDAC
 - Framework required many parts beyond SPAR-H



- **Context for HUNTER**

- ***Origins were in creating a dynamic version of one of the simplest HRA methods, SPAR-H***
- ***Dynamic HRA and PRA have not been widely adapted***
 - The approaches are necessarily complex
 - They have been slow to become releasable software tools
 - A lot of research needed just to get them going
 - The tools have successfully answered many research questions but have not translated into widespread use
- ***If we can create the right tools, dynamic HRA has strong advantages over static HRA***
 - Modeling what-if scenarios that are not possible in static HRA
 - Modeling more realistic contexts and event progressions
 - Providing coupled data between plant models and human models
 - Providing new metrics beyond HEPs
 - E.g., HUNTER calculates time on task in addition to HEPs



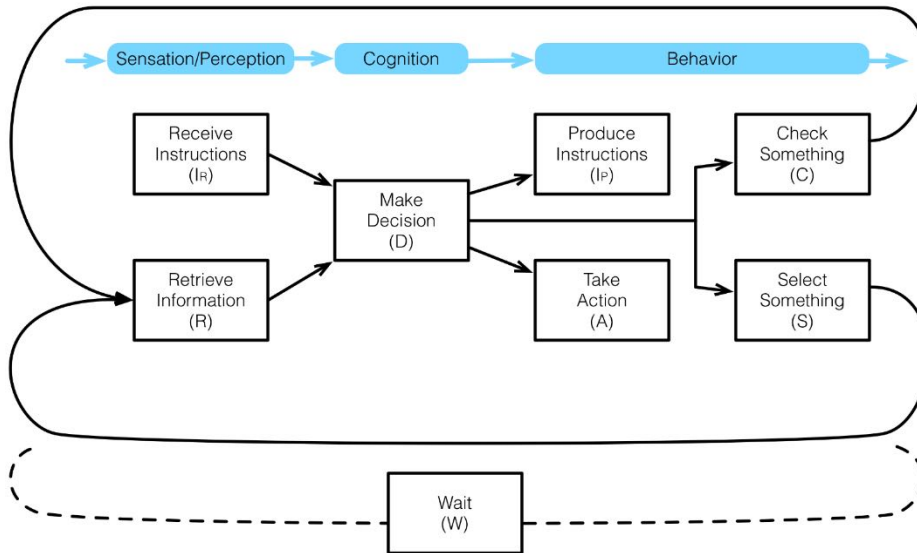
Original HUNTER Elements

- **Original HUNTER Addressed Three Main Concepts**

| Concept | Purpose |
|------------------------|---|
| GOMS-HRA | Taxonomy of task-level primitives that can be paired to operating procedures to provide base error rates and timing for each human action |
| PSF Autocalculation | Calculate modifiers on HEPs based on objective plant conditions that realistically change over an event |
| Dynamic Dependency | Method to aggregate HEPs across multiple tasks for backwards compatibility to static HRA |

- **GOMS-HRA**

- GOMS (Goals-Operators-Methods-Selection rules) was method developed to support task analysis
- GOMS-HRA is INL method to develop a taxonomy of basic elements of human performance



| Term | Abbreviation | Definition |
|---------------------------|--------------|---|
| Task Level Primitive | TLP | A basic human operation occurring at the subtask level. Multiple operations are typically required to achieve specific actions and goals. |
| Procedure Level Primitive | PLP | A human activity occurring at the procedure step level. Often, multiple task level primitives will be required to achieve a procedure level primitive activity. |
| Task Level Error | TLE | A nominal human error associated with a task level primitive. Each task level primitive is associated with multiple possible task level errors. |

Original HUNTER Elements

- **GOMS-HRA**

- GOMS Task Level Primitives provide basic error rates, calibrated to THERP or SPAR-H

| Operator | Description | Nominal HEP | THERP Source | Notes |
|----------------|--|-------------|--------------|-----------------------------------|
| A _C | Performing required physical actions on the control boards | 0.001 | 20-12 (3) | Assume well-delineated controls |
| A _F | Performing required physical actions in the field | 0.008 | 20-13 (4) | Assume series of controls |
| C _C | Looking for required information on the control boards | 0.001 | 20-9 (3) | Assume well-delineated indicators |
| C _F | Looking for required information in the field | 0.01 | 20-14 (4) | Assume unclear indication |
| R _C | Obtaining required information on the control boards | 0.001 | 20-9 (3) | Assume well-delineated indicators |
| R _F | Obtaining required information in the field | 0.01 | 20-14 (4) | Assume unclear indication |
| I _P | Producing verbal or written instructions | 0.003 | 20-5 (1) | Assume omit a step |
| I _R | Receiving verbal or written instructions | 0.001 | 20-8 (1) | Assume recall one item |
| S _C | Selecting or setting a value on the control boards | 0.001 | 20-12 (9) | Assume rotary style control |
| S _F | Selecting or setting a value in the field | 0.008 | 20-13 (4) | Assume series of controls |
| D _P | Making a decision based on procedures | 0.001 | 20-3 (4) | Assume 30-minute rule |
| D _W | Making a decision without available procedures | 0.01 | 20-1 (4) | Assume 30-minute rule |

- **GOMS-HRA**

- GOMS also provides nominal timing data in addition to human error probabilities
- Derived from studies conducted in INL's Human Systems Simulation Laboratory

| Task-Level Primitive | Distribution | Mean (log scale) | Standard Deviation (log scale) | 5 th Percentile | 95 th Percentile |
|----------------------|--------------|------------------|--------------------------------|----------------------------|-----------------------------|
| A _C | Lognormal | 2.23 | 1.18 | 1.32 | 65.30 |
| C _C | Lognormal | 2.14 | 0.76 | 2.44 | 29.90 |
| D _P | Exponential | 0.02 | N/A | 2.62 | 152.80 |
| I _P | Lognormal | 2.46 | 0.76 | 3.35 | 40.70 |
| I _R | Lognormal | 1.92 | 0.93 | 1.47 | 31.80 |
| R _C | Lognormal | 2.11 | 0.60 | 3.08 | 21.90 |
| S _C | Lognormal | 2.93 | 1.11 | 3.01 | 115.60 |
| W | Lognormal | 2.66 | 1.26 | 1.79 | 113.60 |

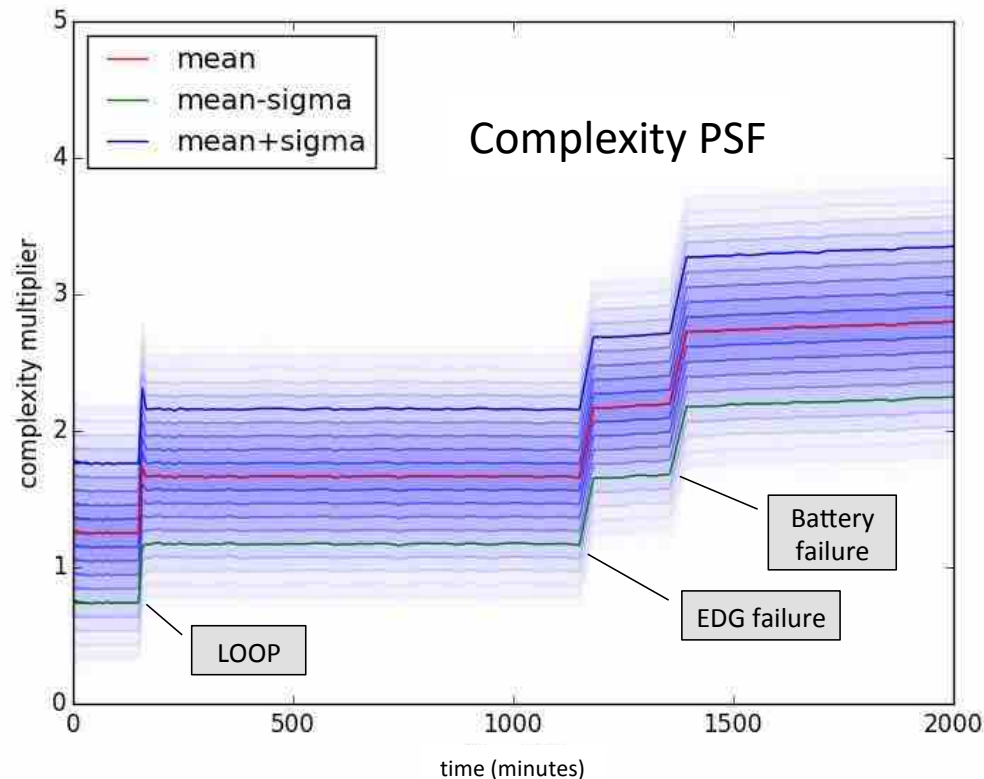
Original HUNTER Elements

- **GOMS-HRA**

- GOMS Task Level Errors map common types of errors that occur

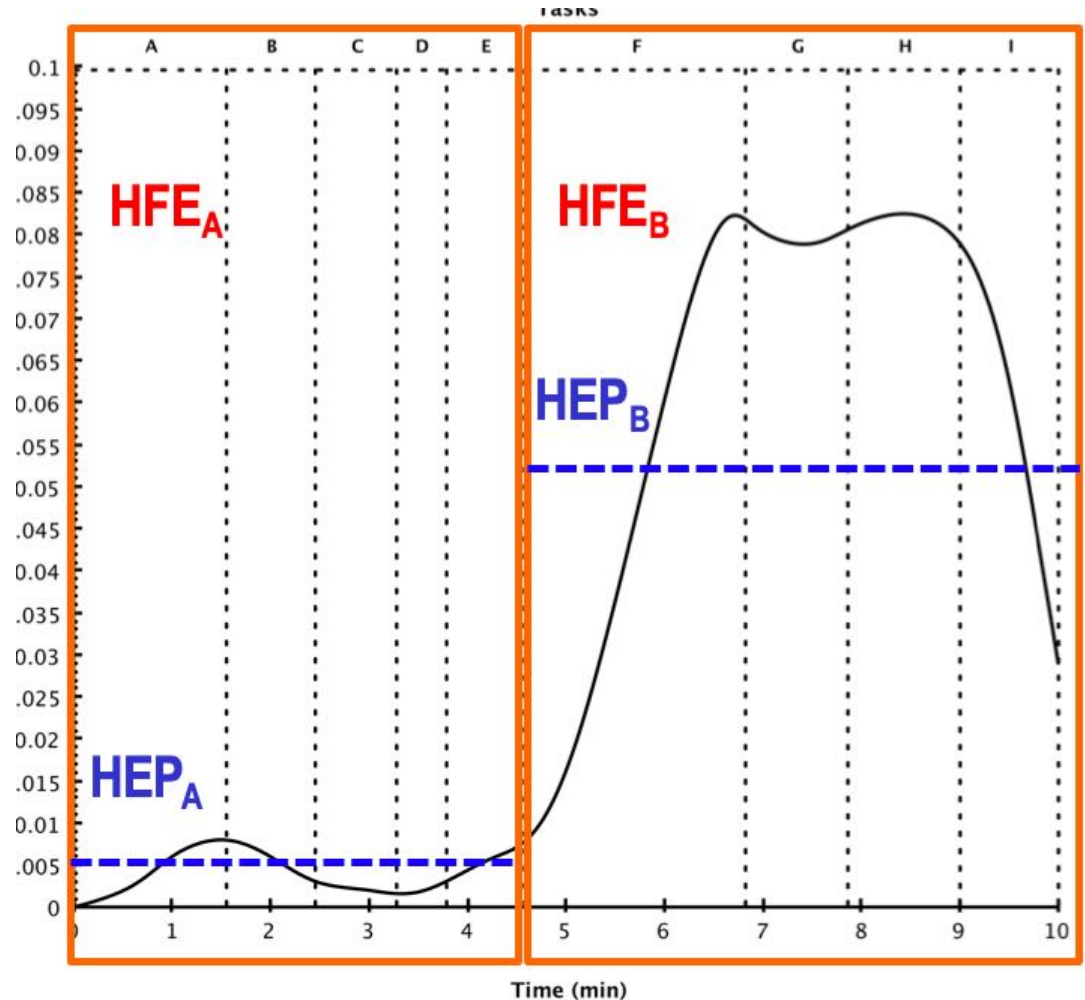
| TLP | Task Level Errors |
|------------|---|
| <i>A</i> | TLE-A1: Failure to execute desired action TLE-A2: Execute desired action incorrectly |
| <i>C</i> | TLE-C1: Wrong information checked TLE-C2: Information missed TLE-C3: Information misinterpreted TLE-C4: Failure to check information |
| <i>R</i> | TLE-R1: Information not attended to TLE-R2: Information not perceived TLE-R3: Information misinterpreted |
| <i>IP</i> | TLE-IP1: Failure to produce desired communication TLE-IP2: Failure to produce correct communication |
| <i>IR</i> | TLE-IR1: Communication not attended to TLE-IR2: Communication not perceived TLE-IR3: Communication misinterpreted |
| <i>S</i> | TLE-S1: Failure to select TLE-S2: Selection make incorrectly |
| <i>D</i> | TLE-D1: Incorrect goals or priorities TLE-D2: Incorrect use of information TLE-D3: Incorrect mental model |
| <i>W</i> | TLE-W1: Incorrect inaction TLE-W2: Waiting too long TLE-W3: Waiting too short |

- **Autocalculation of SPAR-H Performance Shaping Factors (PSFs)**
 - Use plant parameters to calculate influence of PSF on the nominal error rate
 - PSF is calculated without analyst intervention



- **HUNTER Mapping of Dynamic Dependency**

- Dynamic HRA consists of continuous not discrete action sequences
- Traditional static ways of calculating discrete human error probabilities (HEPs) for human failure events (HFEs) may not carry over to dynamic models



- **HUNTER Mapping of Dynamic Dependency**
 - What are the effects of one task on another?
 - PSFs do not just turn on and off; they lag and linger

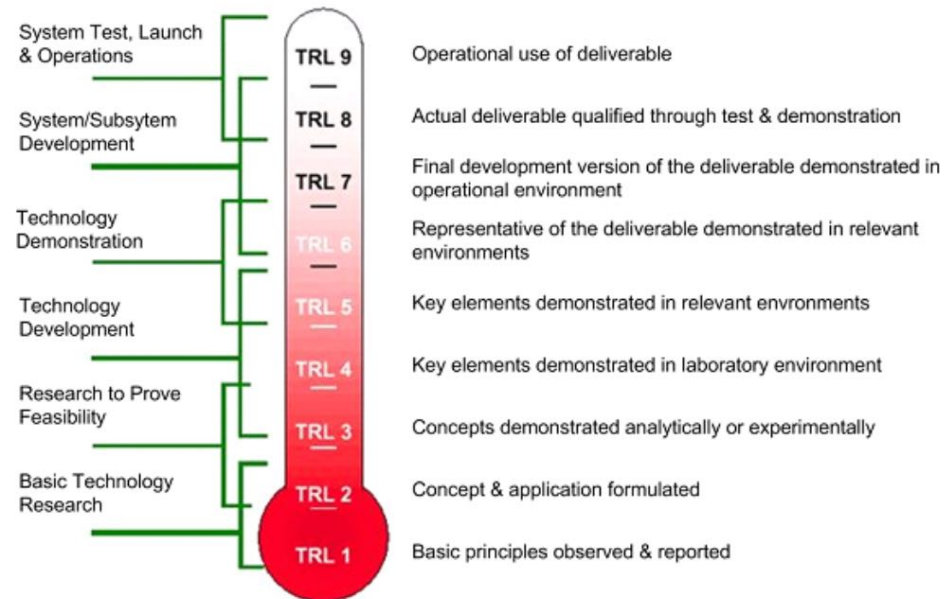
| Dynamic PSF Function | Effect on PSF | Notation |
|----------------------|--|--|
| lag | A PSF will be slow to change at the outset of a new effect | $PSF(t_{i+1}) = \lim_{t \rightarrow t_{i+1}}^- PSF(t)$ |
| linger | A PSF will be slow to change at the termination of an existing effect | $PSF(t_{i+1}) = \lim_{t \rightarrow t_{i+1}}^+ PSF(t)$ |
| memory | General form of lag and linger, denoting that the effect of the current PSF is a function of preceding values for that PSF | $PSF(t_{i+1}) = f(t_i)$ |
| decay | A PSF will settle to its original state over time | $PSF(t) = PSF(0) \quad \text{for } t \gg t_N$ |



New HUNTER Developments

Toward HUNTER 2.0

- **The Original HUNTER was a Disparate Collection of Research Tools**
- **A Review of the Technology Readiness Level of HUNTER Suggested These Parts Were Mature, but the Overall Tool Was Not Complete**
 - HUNTER needs to be developed as a standalone software program
 - HUNTER needs to have a library of analyses
 - Addressing these issues will help make HUNTER a useful tool for human reliability analysts



- **New HUNTER Developments**
 - Captured in report released by DOE LWRS in March 2022
 - Includes refined overall framework
 - Standalone software
 - Emphasis on simplified graphical user interface that promotes ease of use
 - New use case to demonstrate capabilities
 - Clear delineation between HUNTER dynamic HRA and dynamic PRA software like EMERALD

INL/RPT-22-66564

Light Water Reactor Sustainability Program

Software Implementation and Demonstration of the Human Unimodel for Nuclear Technology to Enhance Reliability (HUNTER)



March 2022

U.S. Department of Energy
Office of Nuclear Energy

- **Software Architecture Emphasizes Adaptability**

- ***Flexible***

- HUNTER should be able to model a variety of applications
- From main control room to balance of plant
- Much of the advantage of dynamic HRA may be realized in areas not yet captured by static HRA

- ***Modular***

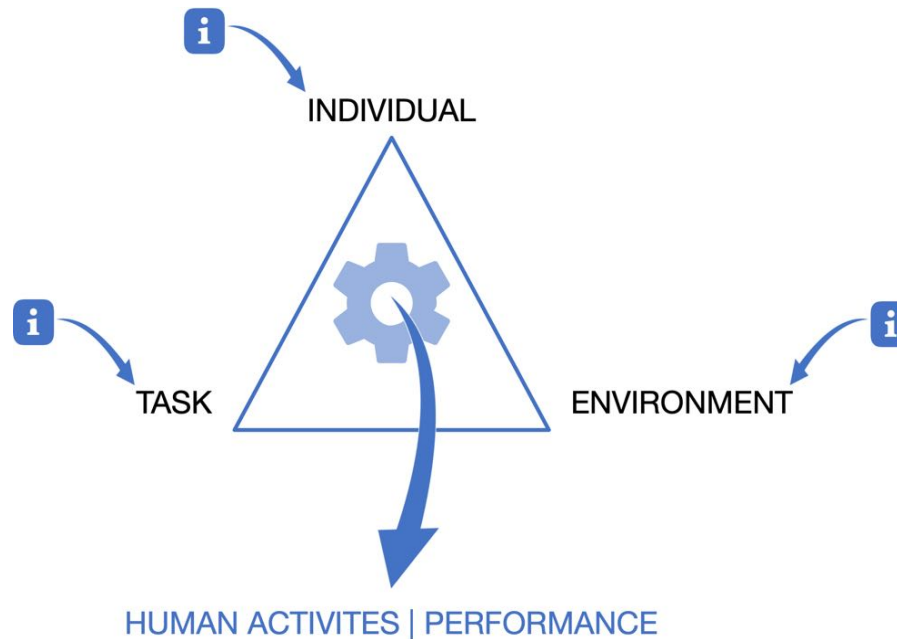
- HUNTER code should not be fixed to one HRA method
- Initial efforts have centered on SPAR-H and new GOMS-HRA
- Should be able to align with other HRA methods like IDHEAS or IDAC

- ***Scalable***

- Features can be added in the future as they are developed
- Features can be turned on or off depending on the granularity of analysis

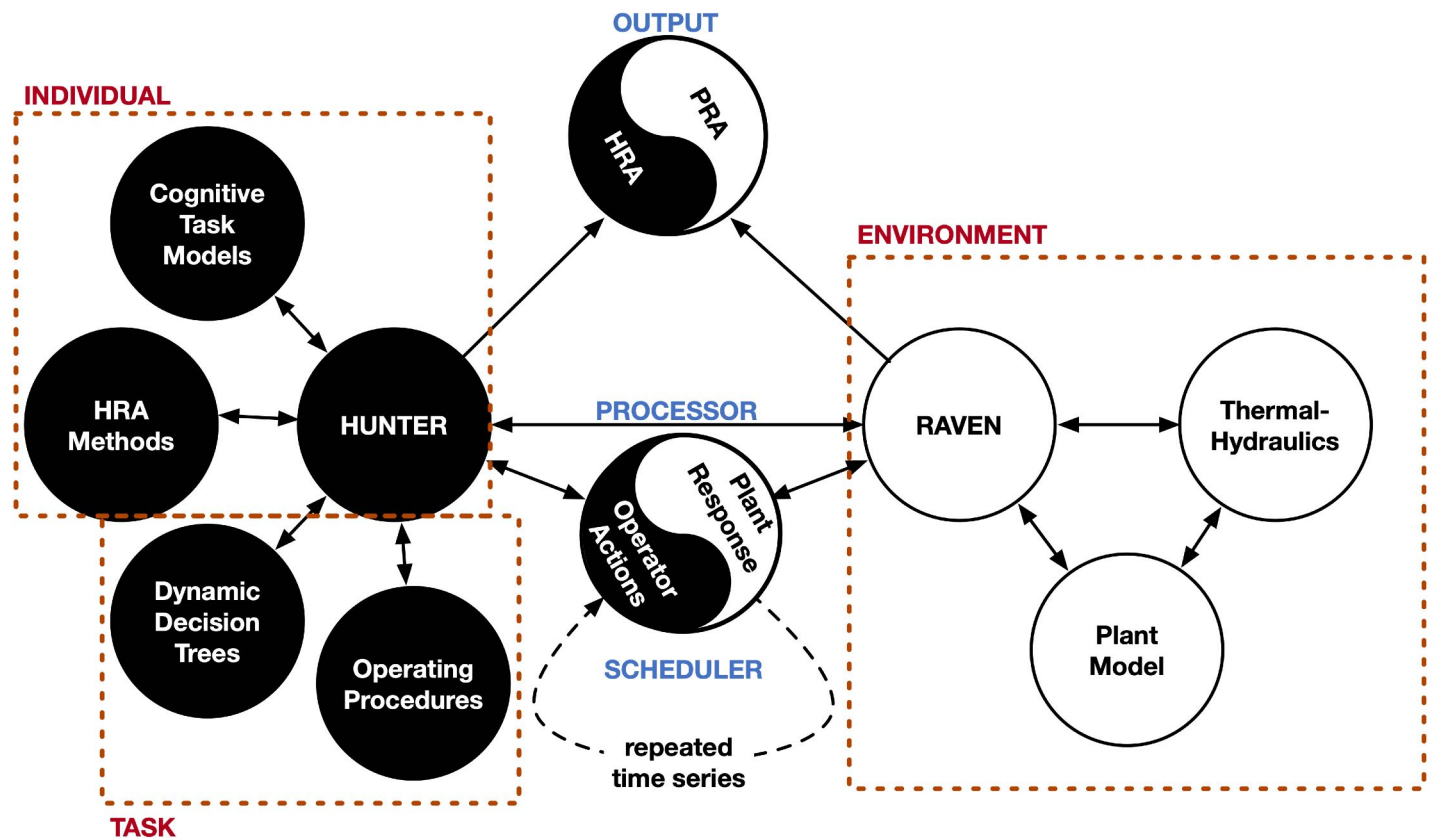
- **New Conceptual Model**

- Three basic modules
 - **Individual:** What affects person performing the task (PSFs)
 - **Task:** What task is being performed (procedures)
 - **Environment:** What system is being used (plant model)



- **HUNTER 2.0 Maps to the Original HUNTER**

- Note that blue are support classes



• Task Module

- Built on plant operating procedures (task = procedure step)
 - Steps mapped to GOMS-HRA task level primitives
 - Steps have input and output to environment such as controls and indicators
- Logic to handle if-then and response not obtained

| stepNumber | isRno | stepText | branchStep | branchProcedure | procedureExit | simulationExit | withinTarget |
|------------|-------|---|------------|-----------------|---------------|----------------|--------------|
| 1 | | Verify Reactor Trip | | | | | TRUE |
| 2 | | Check Turbine Trip - ALL THROTTLE VALVES SHUT | | | | | TRUE |
| 3 | | PERFORM the following: | | | | | TRUE |
| 3 | | | | | | | TRUE |
| 4 | | Safety Injection - ACTUATED (BOTH TRAINS) | | | | | TRUE |
| 5 | | Evaluate EAL Matrix. | | | | | TRUE |
| 6 | | Verify CSIPs - ALL RUNNING | | | | | TRUE |
| 7 | | Verify RHR Pumps - ALL RUNNING | | | | | TRUE |
| 8 | | Safety Injection flow - GREATER THAN 200 GPM | | | | | TRUE |
| 9 | | RCS Pressure - LESS THAN 230 PSIG | | | | | TRUE |
| 9 | TRUE | GO TO Step 12. | 12 | | | | TRUE |
| 12 | | Main Steam Line Isolation - ACTUATED | | | | | TRUE |
| 12 | TRUE | Perform the following: | | | | | TRUE |
| 12 | TRUE | | 16 | | | | FALSE |
| 12 | TRUE | | | | | | TRUE |
| 16 | | Check CNMT Pressure - HAS REMAINED LESS THAN 10 PSIG | | | | | TRUE |
| 17 | | Verify AFW flow - AT LEAST 210 KPPH ESTABLISHED | | | | | TRUE |
| 18 | | Sequencer Load Block 9 (Manual Loading Permissive) - ACTUATED (BOTH TRAINS) | | | | | TRUE |
| 19 | | Energize AC buses 1A1 AND 1B1. | | | | | TRUE |
| 20 | | Verify Alignment Of Components From Actuation Of ESFAS Signals Using Attachment 3, "Safeguards Actuation Verification", While Continuing With This Procedure. | | | | | TRUE |
| 21 | | Stabilize AND Maintain Temperature Between 555F AND 559F Using Table 1. | | | | | TRUE |
| 22 | | PRZ PORVs - SHUT | | | | | TRUE |
| 23 | | PRZ Spray Valves - SHUT | | | | | TRUE |
| 24 | | PRZ PORV Block Valves - AT LEAST ONE OPEN | | | | | TRUE |
| 25 | | Any SG pressure - DROPPING IN AN UNCONTROLLED MANNER OR COMPLETELY DEPRESSURIZED | | | | | TRUE |
| 25 | TRUE | GO TO Step 27. | 27 | | | | TRUE |
| 27 | | Any SG - ABNORMAL RADIATION OR UNCONTROLLED LEVEL RISE | | | | | TRUE |
| 28 | | Check Feed Flow To Ruptured SG(s) - ISOLATED | | | | | TRUE |
| 29 | | GO TO E-3, "STEAM GENERATOR TUBE RUPTURE", Step 1. | | EOP-3 | TRUE | TRUE | TRUE |

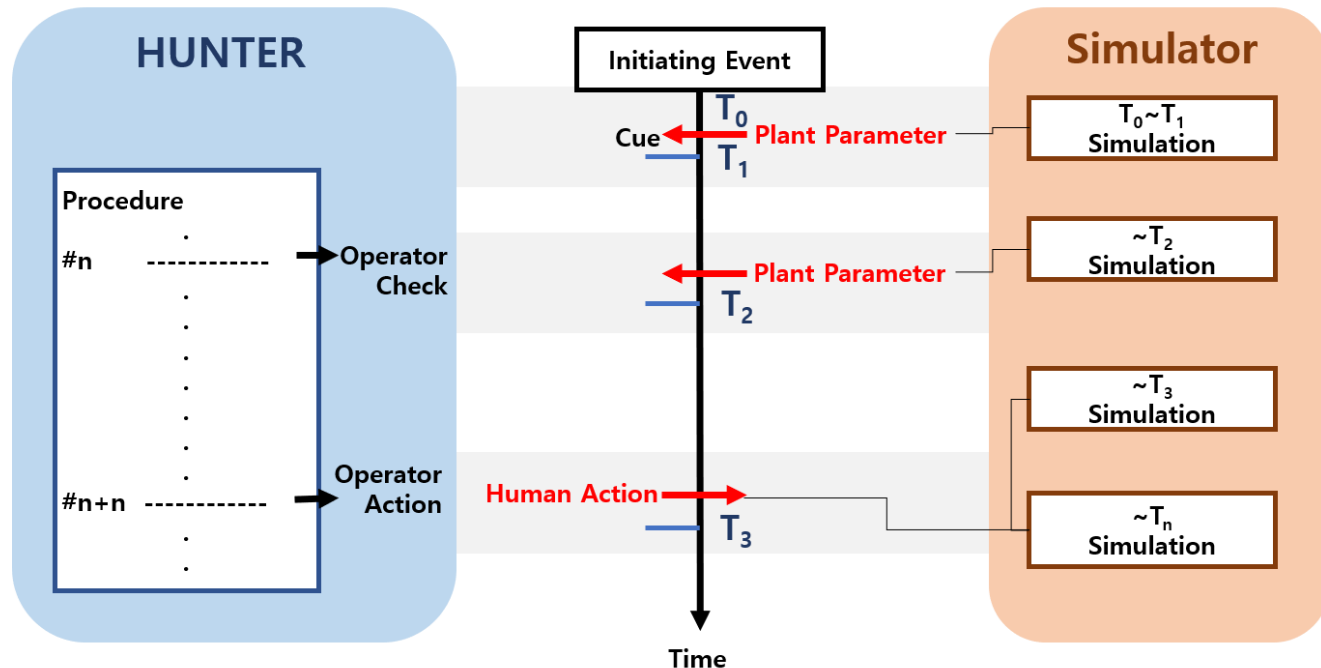
- **Individual Module**

- Currently handles PSFs based on SPAR-H
- Dynamic implementations for Stress, Fitness for Duty (Fatigue), and Available Time
 - Not all PSFs lend themselves to dynamic assignment, but may have trigger points (e.g., upset event at plant)
 - Even manually triggered PSFs may have lag and linger effects

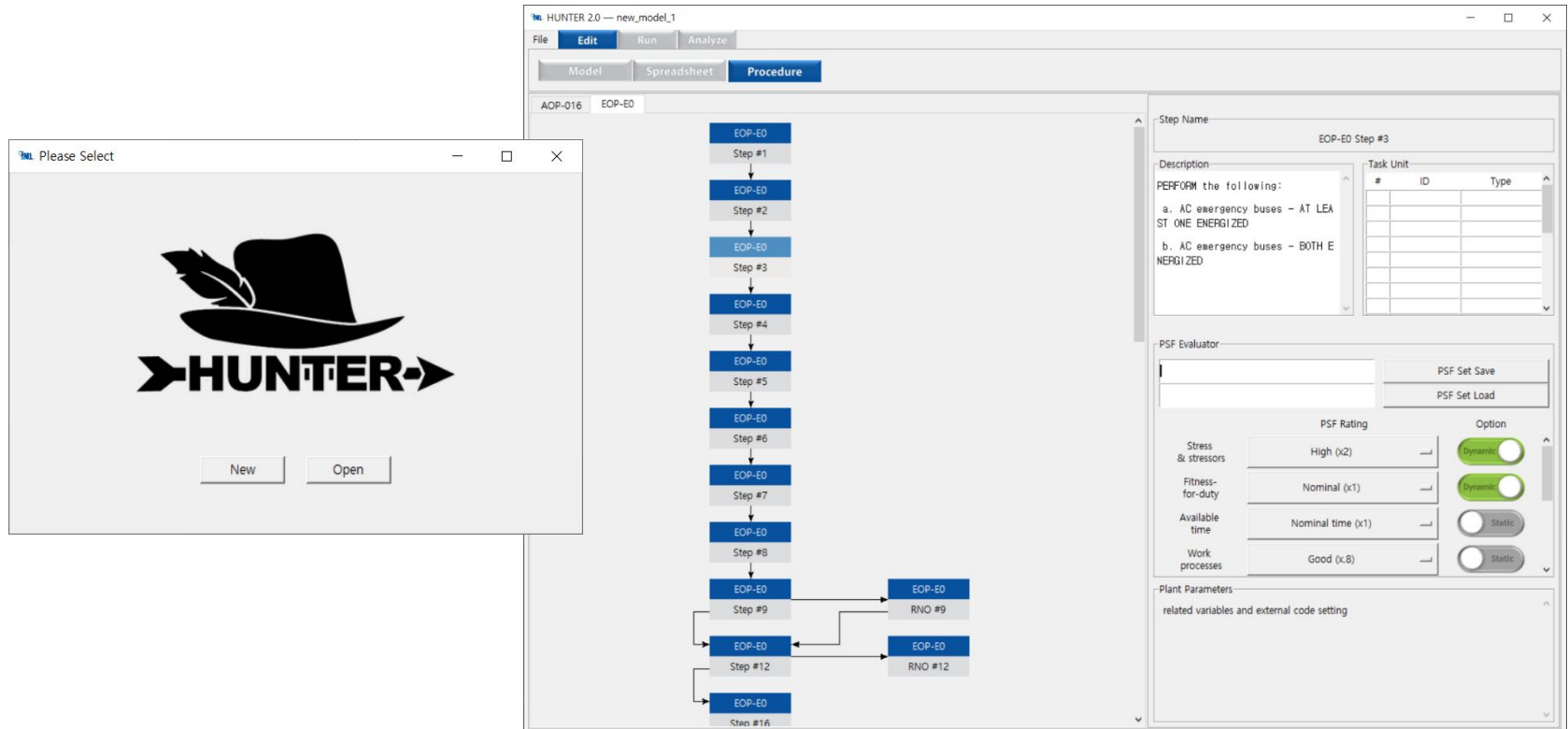
| | | Qualification Function | |
|-------------------------|---------|--|---|
| | | Manually Assigned | Automatically Assigned |
| Quantification Function | Static | The level of the PSF and its multiplier are manually assigned in the model, equivalent to static HRA. | The level of the PSF is automatically assigned, and static (i.e., predefined) multipliers are applied for each level. |
| | Dynamic | The level of the PSF is manually assigned, but the multiplier is automatically calculated (e.g., adjusted for lag and linger effects). | The level of the PSF is automatically assigned and the PSF multiplier is autocalculated. |

- Environment Module**

- HUNTER represents a virtual operator who must interact with a virtual world
- Current focus has been on coupling HUNTER with RELAP5-3D thermalhydraulics
- Tight coupling means operator action triggers change in model and operator responds to changes in plant parameters



- **Graphical User Interface**
 - Python-based code that integrates various parts of HUNTER



The screenshot displays the HUNTER 2.0 software interface. On the left, a dialog box titled "Please Select" features the HUNTER logo (a hat with a feather and the word "HUNTER" with arrows) and buttons for "New" and "Open". The main window shows a flowchart of EOP-E0 steps (Step #1 to Step #16) and RNO nodes (RNO #9, RNO #12). The right panel displays configuration options for "EOP-E0 Step #3", including a description, a task unit table, PSF evaluator settings (Stress & stressors, Fitness-for-duty, Available time, Work processes), and plant parameters.

Task Unit Table:

| # | ID | Type |
|---|----|------|
| | | |
| | | |
| | | |
| | | |
| | | |
| | | |
| | | |
| | | |
| | | |
| | | |

PSF Rating Table:

| Option | PSF Rating |
|--------------------|-------------------|
| Stress & stressors | High (x2) |
| Fitness-for-duty | Nominal (x1) |
| Available time | Nominal time (x1) |
| Work processes | Good (x.8) |



Sample HUNTER Outputs

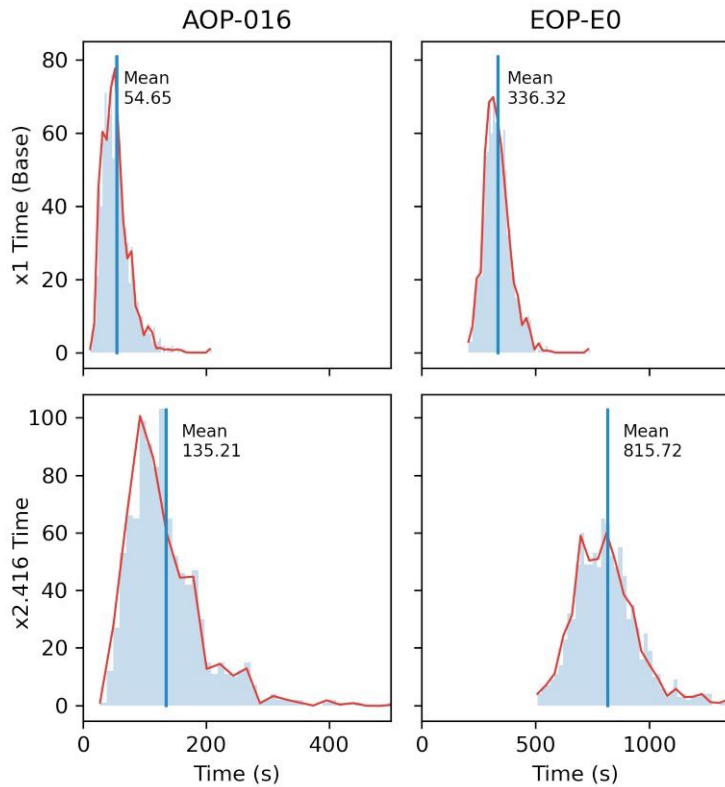
- **Modeled Steam Generator Tube Rupture**

- Example scenario well documented in HRA (e.g., *International HRA Empirical Study*, NUREG/IA-0216)
- Scenario frequently run in INL's simulator with available log parameters for validation
- Example presented here is from NUREG/IA-0216
 - Focus on modeling simple (HFE-1A) and complex (HFE-1B) identification and isolation of ruptured steam generator

| HFE | Descriptions | Base case | Complex case |
|-------|---|-----------|--------------------|
| HFE-1 | Failure to identify and isolate the ruptured SG | HFE-1A | HFE-1B |
| HFE-2 | Failure to cool down the RCS expeditiously | HFE-2A | HFE-2A |
| HFE-3 | Failure to depressurize the RCS expeditiously | HFE-3A | HFE-3B |
| HFE-4 | Failure to stop the safety injection (SI) | HFE-4A | N/A |
| HFE-5 | Failure to give a closing order to the PORV block valve | N/A | HFE-5B1 HFE-5B2 |

- Modeled Steam Generator Tube Rupture

- Time for simple and complex scenarios



| | Mean Time (s) | | |
|---------------|---------------|---------|-------------|
| | Basic | Complex | |
| NUREG/IA-0216 | 370 | 894 | |
| HUNTER | 391 | 951 | ×2.416 Time |



Next Steps



Future Developments in HUNTER

- **Task Module**

- Auto parsing of PDF procedures to populate more scenarios
- Building decision-making module using cognitive modeling
- Building continuous actions

- **Individual Module**

- More PSFs modeled
- Expanding PSFs with effects for both time and error

- **Environment Module**

- Coupling HUNTER with additional external codes
 - Rancor Microworld Simulator
 - GSE Systems Generic Pressurized Water Reactor (GPWR)

- **Other**

- Population of greater number of scenarios
 - HRA for novel applications like design and procedure verification and first-of-a-kind steam extraction
 - Reusable scenarios to benefit industry
- Consideration of other HRA methods beyond underlying SPAR-H
 - IDHEAS? Phoenix? Petro-HRA?



How You Can Help

- **What modeling scenarios are not currently being covered that we can use for demonstrations?**
 - We are not trying to replace static HRA—just enhance it where it makes sense
- **What analysis outputs other than HEPs are needed?**
- **What software does HUNTER need to integrate with to be useful?**
 - Simulators?
 - PRA software?



Questions?

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